

# THE AP1694AS-13 IS <u>OBSOLETE</u>. PLEASE USE THE <u>AL1666A</u>.



AP1694AS-13

## OFFLINE, HIGH PF, HIGH EFFICIENCY DIMMABLE LED DRIVER CONTROLLER

## **Description**

The AP1694AS-13 is a high-performance AC-DC power factor corrector for mains dimmable LED driver applications. The device uses pulse frequency modulation (PFM) technology to regulate output current while achieving high power factor and low THD. It operates as a BCM (boundary conduction mode) controller which is good for EMI.

The AP1694AS-13 provides accurate constant current (CC) regulation while removing the opto-coupler and secondary control circuitry. It also eliminates the need for loop compensation circuitry while maintaining stability. It can meet the requirement of IEC6100-3-2 harmonic standard.

The AP1694AS-13 features low startup current and low operation current. It adopts valley on switching mode to achieve high efficiency. It also has rich protection features including overvoltage, short circuit, and overtemperature protection.

The AP1694AS-13 provides the dimmable LED driver with a wide dimmer compatibility including leading edge and trailing edge dimmer. The AP1694AS-13 can achieve deep dimming down to 1%, while the dimming curve is compliant with the standard of NEMA SSL6.

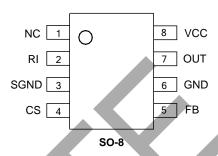
The AP1694AS-13 is available in the SO-8 package.

## **Applications**

Mains dimmable LED lighting

## **Pin Assignments**

#### (Top View)



#### **Features**

- Primary Side Control for Output Current Regulation without Optocoupler
- Boundary Conduction Mode (BCM) Operation to Achieve Highefficiency
- High PF and Low THD (PF > 0.9, THD < 30%)</li>
- High Efficiency without Dimmer
- Wide Range of Dimmer Compatibility
- Dimming Curve Compliant with NEMA SSL6
- Low Startup Current
- Tight LED Current
- Tight LED Open Voltage
- Valley-Mode Switching to Minimize the Transition Loss
- Mosfet Driver up to 25W
- Easy EMI
- Internal Protections:
  - Undervoltage Lockout (UVLO)
  - Leading-Edge Blanking (LEB)
  - Output Short Protection
  - Output Open Protection
  - Overtemperature Protection
- Flexible for Design with Small Form Factor and Very Low BOM Cost
- Totally Lead-Free & Fully RoHS Compliant (Notes 1 & 2)
- Halogen and Antimony Free. "Green" Device (Note 3)
- For automotive applications requiring specific change control (i.e. parts qualified to AEC-Q100/101/104/200, PPAP capable, and manufactured in IATF 16949 certified facilities), please contact us or your local Diodes representative.

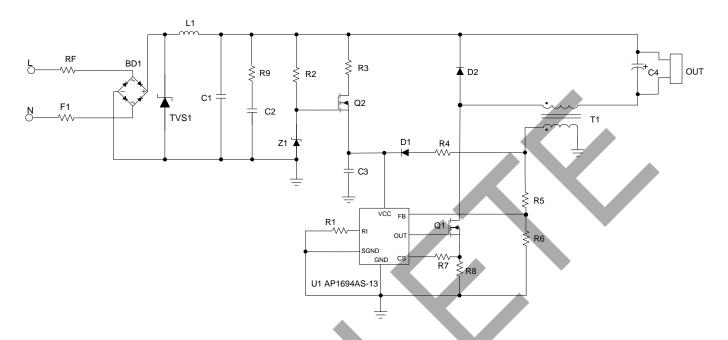
https://www.diodes.com/quality/product-definitions/

Notes:

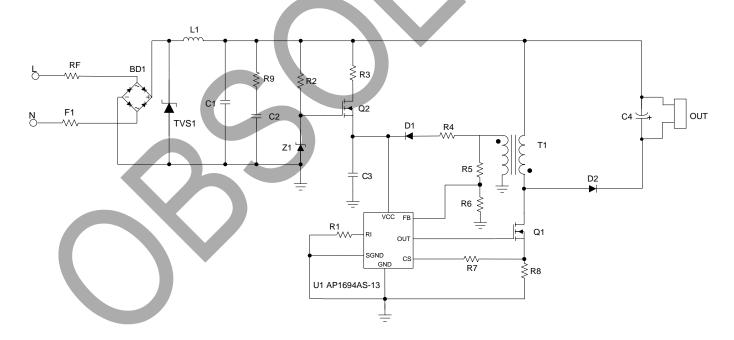
- 1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS), 2011/65/EU (RoHS 2) & 2015/863/EU (RoHS 3) compliant.
- 2. See https://www.diodes.com/quality/lead-free/ for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.
- 3. Halogen- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine (<1500ppm total Br + Cl) and <1000ppm antimony compounds.



# **Typical Applications Circuit**



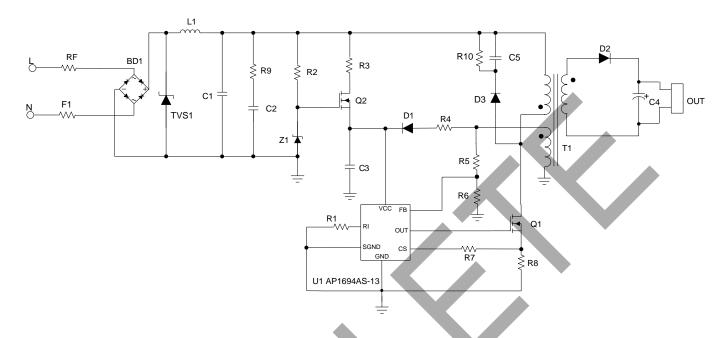
Typical Buck Application



Typical Buck-boost Application



# **Typical Applications Circuit** (continued)



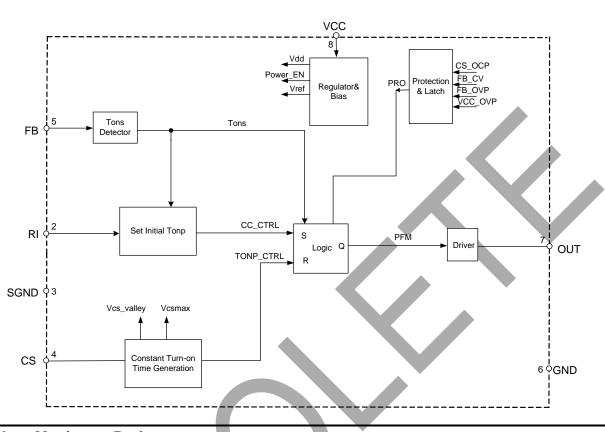
Typical Fly-Back Application

# **Pin Descriptions**

Pin Number	Pin Name	Function	
1	NC	No connection.	
2	RI	The initial on time setting resistor.	
3	SGND	Must connect to GND.	
4	CS	Primary current sensing.	
5	FB	The feedback voltage from auxiliary winding.	
6	GND	Ground.	
7	OUT	Gate driver output.	
8	VCC	Supply voltage of gate driver and control circuits of the IC.	



# **Functional Block Diagram**



# Absolute Maximum Ratings (Note 4) (@TA = +25°C, unless otherwise specified.)

Symbol	Parameter	Rating	Unit
Vcc	Power Supply Voltage	-0.3 to 35	V
Іоит	Driver Output Current	150	mA
Vcs	Voltage at CS to GND	-0.3 to 7	V
V <sub>FB</sub>	FB Input Voltage	-40 to 10	V
TJ	Operating Junction Temperature	-40 to +150	°C
T <sub>STG</sub>	Storage Temperature	-65 to +150	°C
TLEAD	Lead Temperature (Soldering, 10 sec)	+300	°C
P <sub>D</sub>	Power Dissipation (T <sub>A</sub> = +50°C)	0.65	W
θја	Thermal Resistance (Junction to Ambient)	160	°C/W
_	ESD (Human Body Model)	±2,000	V
_	ESD (Machine Model)	±200	V

Note 4: Stresses greater than those listed under *Absolute Maximum Ratings* can cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to *Absolute Maximum Ratings* for extended periods can affect device reliability.



# **Recommended Operating Conditions**

Symbol	Parameter	Min	Max	Unit
Vcc	Power Supply Voltage	7	25	V
Ta	Ambient Temperature	-40	+105	°C

# **Electrical Characteristics** (@T<sub>A</sub> = +25°C, unless otherwise specified.)

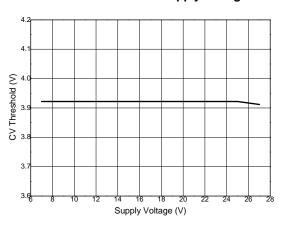
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
UVLO Section						
V <sub>TH</sub> (ST)	Startup Threshold	-	13	14.5	16	V
Vopr (Min)	Minimum Operating Voltage	After turn-on	5.5	6.5	7.5	V
Vcc_ovp	VCC OVP Voltage	-	27	29	31	V
_	VCC Delatch Voltage (Note 5)	-	3	4	5	V
Standby Current Section	1					
Ist	Startup Current	Vcc = Vth (ST) -0.5V, Before start up	-	_	20	μΑ
Icc (OPR)	Operating Current	Static	_	900	1,300	μΑ
Drive Output Section						
VGATE	Gate Voltage		11	12	14	V
I <sub>SOURCE_L</sub>	Low Driver Source Current	-	35	40	45	mA
Isource_H	High Driver Source Current	-	90	100	120	mA
RDS(on)	Sink Resistance	-	6	7	8	Ω
Current Sense Section						
$V_{CS\_REF}$	Current Sense Reference	_	ı	1	_	V
Vcs_clamp	Current Sense Reference Clamp	_	1.2	1.4	_	V
tonp_min	Minimum tonp	_	700	_	1,000	ns
t <sub>D(H-L)</sub>	Delay to Output (Note 5)	_	50	150	250	ns
Feedback Input Section						
lfB	Feedback Pin Input Leakage Current	V <sub>FB</sub> = 2V	-	_	4	μΑ
V <sub>FB_CV</sub>	FB CV Threshold	-	3.8	4	4.2	V
VFB_OVP	FB OVP Threshold	_	4.5	6	7.5	V
Output Current						
-	System Output Current On Final Test Board	_	-	_	±2	%
Overtemperature Protec	tion Section					
_	Shutdown Temperature (Note 5)	_	+150	_	_	°C
_	Temperature Hysteresis (Note 5)	-	_	+20	_	°C

Note 5: These parameters, although guaranteed by design, are not 100% tested in production.

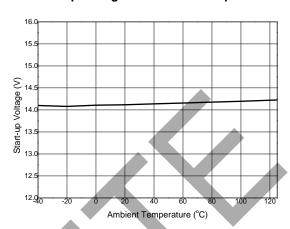


## **Performance Characteristics**

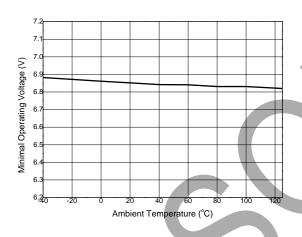
## CV Threshold vs. Supply Voltage



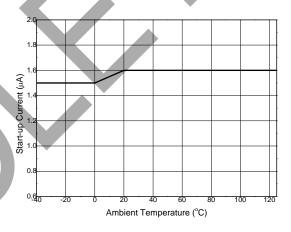
## Startup Voltage vs. Ambient Temperature



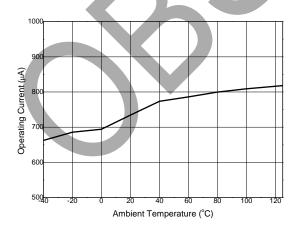
## Minimal Operating Voltage vs. Ambient Temperature



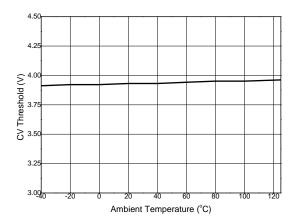
## Startup Current vs. Ambient Temperature



## **Operating Current vs. Ambient Temperature**



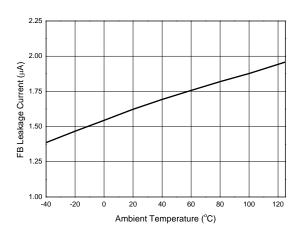
## CV Threshold vs. Ambient Temperature



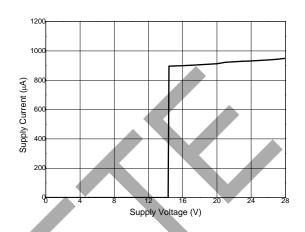


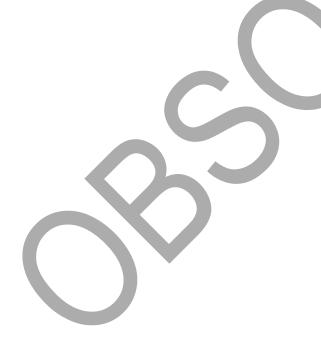
# **Performance Characteristics** (continued)

## FB Leakage Current vs. Ambient Temperature



## Supply Current vs. Supply Voltage







## **Application Information Based on Buck Structure**

The AP1694AS-13 uses constant on time control method within one AC cycle to achieve the high power factor. When the dimmer is connected to the driver, although a part of input voltage is cut off by the dimmer, the system still operates in constant on time mode. In this way, good dimmer compatibility can be realized.

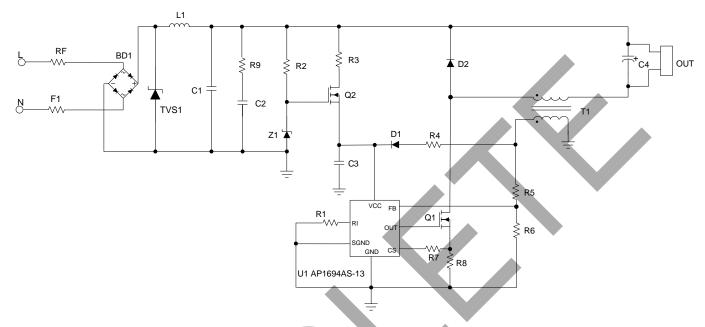


Figure 1. Typical Buck Application Circuit

When the dimmer is connected, and the conduction angle of the dimmer is  $\pi - \alpha$ ; according to the control principle of the IC, the output current can be determined as:

$$I_{o}(\alpha, \theta) = \frac{1}{2} \cdot I_{pk}(\alpha, \theta) = \begin{cases} \frac{1}{2} \cdot \frac{V_{cs_{-ref}}}{R8} \cdot \sin(\theta) & \text{if } (\theta > \alpha) \\ 0 & \text{else} \end{cases}$$

In consideration of the dead zone of the buck structure, the output current DC value can be calculated as below:

$$I_{o_{-mean}} = k \cdot \frac{1}{\pi} \int_{0}^{\pi} I_{o}(\alpha, \theta) d\theta$$

Where,

 $V_{cs\ ref}$  is the reference of the current sense, and the typical value is 1V.

lpha is the cutoff angle of dimmer.

heta is the phase of the input voltage.

k is the current modification coefficient, and the value is approximate to be 0.7.

When no dimmer is connected with the driver ( lpha=0 ), the output current DC value can be calculated by:

$$I_{o\_mean} = k \cdot \frac{1}{\pi} \cdot \frac{V_{cs\_ref}}{R8}$$



# **Application Information Based on Buck Structure** (continued)

## **Design Parameters**

#### **Setting the Current Sense Resistor R8**

According to the equation of the output current, the current sense resistor R8 is determined:

$$R8 = k \cdot \frac{V_{cs\_ref}}{\pi \cdot I_{o\ mean}}$$

#### **Transformer Selection**

The typical non-isolated buck circuit in Figure 1 is usually selected, and the system is operating at boundary conduction mode. The switching frequency at the crest is set as f<sub>min</sub>, the inductance can be calculated as below:

$$L = \frac{(\sqrt{2} \cdot V_{in\_rms} - V_o) \cdot R8 \cdot V_o}{V_{cs\_ref} \cdot \sqrt{2} \cdot V_{in\_rms} \cdot f_{\min}}$$

Where,

 $V_o$  is the output voltage.

 $V_{in\ rms}$  is the RMS value of the input voltage.

According to Ferrari's law of electromagnetic induction, the winding turns number of the buck inductance N<sub>L</sub> is:

$$N_{L} = \frac{L \cdot i_{pk}}{A_{e} \cdot B_{m}} = \frac{L \cdot V_{cs\_ref}}{A_{e} \cdot B_{m} \cdot R8}$$

Where.

 $A_{a}$  is the core effective area.

 $B_m$  is the maximum magnetic flux density.

The auxiliary winding is the power supply for Vcc, the winding turns number Naux is:

$$N_{aux} = N_L \cdot \frac{V_{cc}}{V_c + V_d}$$

Where.

Vcc is the power supply voltage for IC from auxiliary winding.

V<sub>d</sub> is the voltage drop of the freewheel diode.

## Setting the Initial On Time

As the AP1694AS-13 adopts the constant on time control method, the AP1694AS-13 will generate an initial on time to start a working cycle. If the initial on time is longer than the rated on time, overshoot will happen. The initial on time is determined by resister R1 shown in Figure 1.

According to the initial on time generation mechanism, the ton\_initial is:

$$t_{on\ initial} = 80 \cdot R1 \cdot 10^{-12} s$$

To guarantee the system with no overshoot phenomenon, the resistor R1 is selected:

$$R_{1} \le \frac{1.25 \cdot L}{R8 \cdot \sqrt{2} U_{in\_rms\_max}} \cdot 10^{10} \Omega$$



## **Application Information Based on Buck Structure (continued)**

In dimmable application, on the condition of the acceptable line regulation, the smaller R1 is selected, as it will be better for dimming performance.

#### **Valley On Control Method**

The valley on function can provide low turn-on switching losses for buck converter. The voltage across the power-switch is reflected by the auxiliary winding of the buck transformer. The voltage is sensed by FB pin.

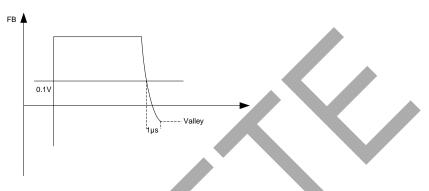


Figure 2. Valley On-Control

According to Figure 2, when the falling edge of 0.1V is sensed by FB pin, the AP1694AS-13 will see the toff time is over and delay 1µs to start a new operating cycle. By this way we can realize valley on function.

#### Passive Damping and Bleeder Design

The passive bleeder is designed to supply latching and holding current to eliminate misfire and flicker.

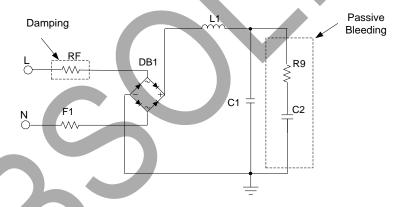


Figure 3. LED Driver Schematic with Passive Bleeder

A passive bleeder is composed of a resister (R9) and a capacitor (C2). C1 is input filter capacitor and RF is damper resistor.

The passive bleeder includes a capacitor (C2, hundreds of nF) to provide latching current. To remove the voltage and current spike, a resistor (R9) is necessary to dampen the spike.

In dimmable application, because a large C2 will affect the PF, THD and efficiency, the value of the capacitor (C2) selected should be suitable. Generally, 100nF/400V to 330nF/400V is recommended.

RF is the damper for reducing the spike current caused by quick charging of C2 at firing. RF is selected from  $20\Omega$  to  $100\Omega$  for low-line application, and  $51\Omega$  to  $200\Omega$  for high-line application. If R9 is too small, R9 can't fully dampen the spike current and ringing current will occur. The ringing current will cause the TRIAC misfire which will cause LED flicking. Another consideration in R9 selection is power loss; an R9 that is too large will make more power dissipation. Generally, a  $200\Omega$  to  $2K\Omega$  resistor is selected for R9.



## **Application Information Based on Buck Structure** (continued)

Fault Protection
Overvoltage Protection and Output Open Protection

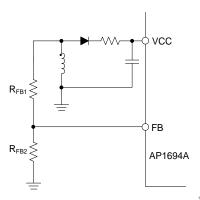


Figure 4. OVP Circuit

The output voltage is sensed by the auxiliary winding voltage of the Buck transformer. The VCC pin and FB pin provide overvoltage protection function. When the output is open or large transient happens, the output voltage will exceed the rated value. When the voltage of  $V_{CC\_OVP}$  or  $V_{FB\_CV}$ , the overvoltage is triggered and the IC will discharge  $V_{CC}$ . When the  $V_{CC}$  is below the UVLO threshold voltage, IC will start a new work cycle and the  $V_{CC\_OAP}$  is charged again by start resistance. If the overvoltage condition still exists, the system will work in hiccup mode.

Attention: If the external fast startup circuit is adding in the application and the overvoltage protection and output open protection happen, the IC will trigger latch.

#### **Output Short Protection**

When the output is shorted, the output voltage will be clamped at zero. At this condition, Vcc will drop down without auxiliary winding for power supply, and the Vcc will drop to UVLO threshold voltage. The IC will shut down and restart a new operating cycle, and the Vcc is charged by startup resistance. When Vcc is higher than Vcc\_start voltage, IC will output a bunch of pulses to control power switch on and off. When still no FB signal detected, the device will not output more pulses. The Vcc will again drop to Vcc UVLO threshold. If output short condition still exists, the system will operate in hiccup mode.

Attention: If the external fast startup circuit is adding in the application, the device will not work at UVLO mode, and the device will work at minimum toff mode.

#### **Overtemperature Protection**

AP1694AS-13 has two kinds of overtemperature protection processes. First, if the system is operating normally, the ambient temperature is changed to +170°C, and suddenly the IC will trigger overtemperature protection which leads to a latch work mode. Second, if the system starts when the ambient temperature is higher than +150°C, overtemperature protection will be triggered. So, the AP1694AS-13 can startup successfully when the ambient temperature is less than +150°C.

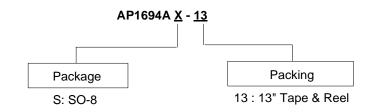
## **Components Selection Guide**

If the system's spec is changed, please refer to the design sheet of the AP1694AS-13 and select the compatible system parameter. When the system needs to be adjusted slightly, please refer to the table below and adjust the value of the related component.

Item	Description	Related Components	
lo	Output current	R8	
Output Current Ripple	Small current ripple is good for LED life	C4	
ton_initial	System initial on time, used to startup the system	R1	
Output Open Voltage	Setting the output voltage when the LED is open	R5, R6	
Dimming Performance	Improve the dimming performance	R1, RF, R9, C2, C4	
EMI	Pass EN 55022 class B with 6DB margin	L1, C1	
Line Compensation	To get a good line regulation	R7	

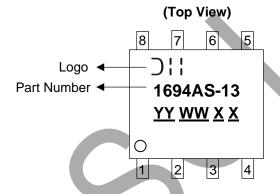


# **Ordering Information**



Ondersta Bart Name	Bashana Cada	Package ·	Packing		
Orderable Part Number	Package Code		Qty.	Carrier	
AP1694AS-13	S	SO-8	4000	13" Tape and Reel	

# **Marking Information**



<u>YY</u>: Year: 15,16,17 ~ <u>WW</u>: Week: 01~52; 52

represents 52 and 53 week

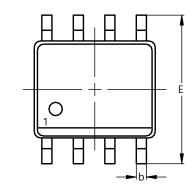
XX: Internal Code

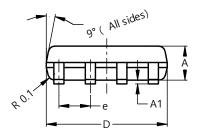


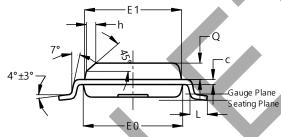
# **Package Outline Dimensions**

Please see http://www.diodes.com/package-outlines.html for the latest version.

## SO-8





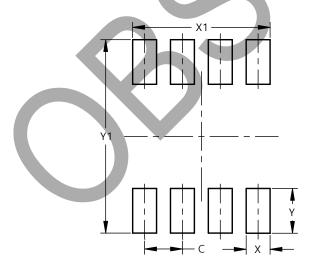


SO-8				
Dim	Min	Max	Тур	
Α	1.40	1.50	1.45	
A1	0.10	0.20	0.15	
b	0.30	0.50	0.40	
С	0.15	0.25	0.20	
D	4.85	4.95	4.90	
ш	5.90	6.10	6.00	
É	3.80	3.90	3.85	
E0	3.85	3.95	3.90	
e		-	1.27	
h	_		0.35	
┙	0.62	0.82	0.72	
ø	0.60	0.70	0.65	
All Dimensions in mm				

# **Suggested Pad Layout**

Please see http://www.diodes.com/package-outlines.html for the latest version.

SO-8



Dimensions	Value (in mm)	
С	1.27	
Х	0.802	
X1	4.612	
Υ	1.505	
Y1	6.50	



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